

Thursday, November 30, 2017

## Radiation Reaction (continued)

Abraham-Lorentz  
formula

$$\vec{F}_{\text{radiation}} = \frac{\mu_0 q^2}{6\pi c} \frac{d\vec{a}}{dt}$$

this is the force of the charge's EM field on the charge

The formula is problematic!  $\Rightarrow$  big outstanding problem  
in classical EM

equation of motion:  $ma = \frac{\mu_0 q^2}{6\pi c} \frac{da}{dt}$

if  $\frac{d\vec{a}}{dt} = 0 \Rightarrow$  ~~the~~

then  $\vec{F}_{\text{radiation}} = 0$   
 $\hookrightarrow$  "false"

$\hookrightarrow$  solution:  $a(t) = a_0 e^{t/\tau}$

with  $\tau = \frac{\mu_0 q^2}{6\pi c m}$

$\Rightarrow$  runaway acceleration

$\hookrightarrow$  contradicts periodic motion  
hypothesis



avoid formula unless you have no choice !!!

$\hookrightarrow$  use conservation of energy (or momentum) to get  
the overall effect of radiation reaction.

# Lorentz Transformation, Special Relativity, and 4-vectors

## Lorentz Transformation

We saw previously that for a moving point charge, the associated scalar & vector potentials, and the associated  $\vec{E}$  &  $\vec{B}$  fields do not transform according to Galilean relativity

### Stationary Point Charge (Lorentz gauge)

Point charge in uniform motion  
( $\vec{v}_0 = v_0 \hat{z}$ )

$$V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{|\vec{r} - \vec{r}_0|} \longrightarrow V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \gamma \frac{1}{\sqrt{x^2 + y^2 + [\gamma(z - v_0 t)]^2}}$$

$$\vec{A}(\vec{r}, t) = 0 \longrightarrow \vec{A}(\vec{r}, t) = \frac{\mu_0 q v_0 \hat{z}}{4\pi} \gamma \frac{1}{\sqrt{x^2 + y^2 + [\gamma(z - v_0 t)]^2}}$$

$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{|\vec{r} - \vec{r}_0|^2} \longrightarrow \vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \gamma \frac{(x, y, z - v_0 t)}{[x^2 + y^2 + [\gamma(z - v_0 t)]^2]^{3/2}}$$

$$\vec{B}(\vec{r}, t) = 0 \longrightarrow \vec{B}(\vec{r}, t) = \frac{\vec{v}_0 \times \vec{E}}{c^2}, \text{ where } \gamma = \frac{1}{\sqrt{1 - (v_0/c)^2}}$$

The coordinates transform according to the Lorentz transformation.

$S'$  is the moving frame ( $\vec{v}_0 = v_0 \hat{z}$ ).  $S$  is the stationary frame.

Lorentz transformation:

$$x' = x$$

$$y' = y$$

$$z' = \gamma(z - v_0 t)$$

also  $t' = \gamma(t - \frac{v_0 z}{c^2})$

} obtain by inspection of equations

less obvious

$V$ ,  $\vec{A}$ ,  $\vec{E}$ , and  $\vec{B}$  obey related transformations  
 $\hookrightarrow$  to be determined.

Motivating Question: Can you get magnetism / Maxwell's equations from the Lorentz transformation and Coulomb's law?

if yes ---- other question: Is there a  $\vec{B}$  equivalent in Gravity?

Einstein's Postulates for Special Relativity:

1 - The principle of relativity: The laws of physics are the same in all inertial reference frames.

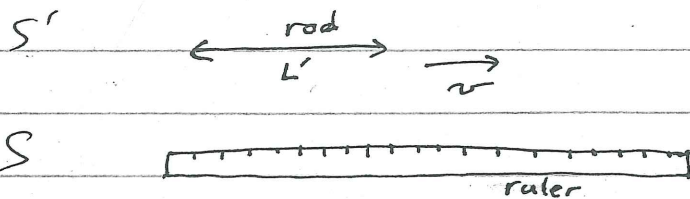
inertial frame = coordinate system at constant velocity

in a rest frame  $\leftarrow$  frame in which you cannot tell that you are accelerating

2 - Universal speed of light: The speed of light in vacuum is the same in all inertial reference frames, regardless of the motion of the source.

Brief Review:

a. Length contraction: consider a rod of length  $L' = L_0$  in the  $S'$  frame moving at  $\vec{v} = v\hat{x}$



How long is the rod in  $S$ ?

(simultaneous measurement of positions of both ends in  $S$ )

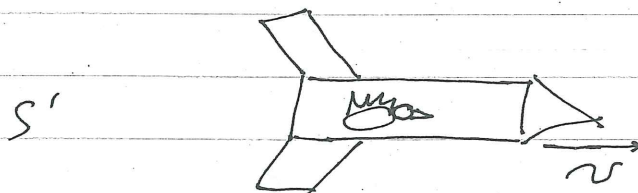
$$\begin{aligned}
 \Delta L' = \Delta z' &= z_2' - z_1' \\
 &= \gamma(z_2 - vt) - \gamma(z_1 - vt) \\
 &= \gamma(z_2 - z_1) \\
 &= \gamma \Delta z
 \end{aligned}$$

$$\hookrightarrow \Delta z = \frac{1}{\gamma} \Delta z' \Rightarrow L = \frac{1}{\gamma} L' \Rightarrow L = \frac{1}{\gamma} L_0$$

The rod is a factor  $1/\gamma$  shorter in  $S$ .

### b. Time dilation

Astronauts on spaceship  $S'$  travelling with velocity  $\vec{v} = v\hat{z}$  are preparing a turkey for Thanksgiving. On the spaceship  $S'$ , they cook the turkey for  $\Delta T' = T_0$ . How long does the turkey cook for in your frame  $S$ ? (Earth's)



$$\begin{aligned}
 \Delta T' = t_2' - t_1' &= \gamma \left( t_2 - \frac{v}{c^2} z_2 \right) - \gamma \left( t_1 - \frac{v}{c^2} z_1 \right) \\
 &= \gamma t_2 \left( 1 - \frac{v^2}{c^2} \right) - \gamma t_1 \left( 1 - \frac{v^2}{c^2} \right) \\
 &= \gamma (t_2 - t_1) \underbrace{\left( 1 - \frac{v^2}{c^2} \right)}_{1/\gamma^2} = \frac{\Delta T}{\gamma}
 \end{aligned}$$

$$\Rightarrow \Delta T = \gamma \Delta T' \Rightarrow T = \gamma T_0$$

The turkey takes a factor of  $\gamma$  longer to cook in  $S$ .

## Lorentz Transformation in Matrix Form

$$\begin{array}{l}
 ct' = \gamma(ct - \frac{v}{c}z) \\
 x' = x \\
 y' = y \\
 z' = \gamma(z - \frac{v}{c}ct)
 \end{array}
 \quad \left| \quad
 \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\beta\gamma & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

$$\beta = \frac{v}{c}$$

$\Lambda(\vec{v} = v\hat{z})$   $\mu \leftarrow$  line  
 $\nu \leftarrow$  column

$S'$  travelling with velocity  $\vec{v} = v\hat{z}$  in  $S$

## 4-vectors

Contravariant vectors:  $a^\mu$

example: position 4-vector  $x^\mu = \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix} = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$

Covariant vectors:  $a_\mu$

example: position 4-vector  $x_\mu = (x_0, x_1, x_2, x_3) = (-ct, x, y, z)$

in general  $a_\mu = (-a^0, a^1, a^2, a^3)$

How do you transform a contravariant 4-vector from one reference frame to another?

$$a^{\mu'} = \sum_{\nu=0}^3 \Lambda(\vec{v})^{\mu}_{\nu} a^{\nu} \equiv \Lambda(\vec{v})^{\mu}_{\nu} a^{\nu}$$

any contravariant 4-vector  $\mu \leftarrow$  line  $\nu \leftarrow$  column

Einstein notation: implied summation over repeated index

$$a^{\mu'} = \Lambda_{\nu}^{\mu'} a^{\nu} = a^{\nu} \Lambda_{\nu}^{\mu'}$$

$$\Leftrightarrow \begin{pmatrix} a^{0'} \\ a^{1'} \\ a^{2'} \\ a^{3'} \end{pmatrix} = \underbrace{\begin{pmatrix} \gamma & 0 & 0 & -\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\beta\gamma & 0 & 0 & \gamma \end{pmatrix}}_{\Delta(\vec{v} = v_3^1)^{\mu}_{\nu}} \begin{pmatrix} a^0 \\ a^1 \\ a^2 \\ a^3 \end{pmatrix}$$

note:  $a^{\mu} = \Lambda(-\vec{v})^{\mu}_{\nu'} a^{\nu'}$

$$\Delta(\vec{v})^{\mu}_{\nu} \Lambda(-\vec{v})^{\nu}_{\mu} = \delta_{\mu}^{\mu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

unsurprisingly  $[\Delta(\vec{v})^{\mu}_{\nu}]^{-1} = \Lambda(-\vec{v})^{\mu}_{\nu}$

Scalar product:

$$\begin{aligned} (a)^2 &= a_{\mu} a^{\mu} = a_0 a^0 + a_1 a^1 + a_2 a^2 + a_3 a^3 \\ &= -(a^0)^2 + (a^1)^2 + (a^2)^2 + (a^3)^2 \end{aligned}$$

$$\begin{aligned} ab &= a_{\mu} b^{\mu} \\ &= -a^0 b^0 + a^1 b^1 + a^2 b^2 + a^3 b^3 \end{aligned}$$

the scalar product of two 4-vectors is Lorentz invariant ↙ in the same frame

(i.e. scalar product does not depend on your reference frame)

Q: How do covariant 4-vectors transform?

$$a'_\mu = \Lambda(-\vec{v})^\nu_{\ \mu} a_\nu$$

↖ line  
↖ column

$$\begin{pmatrix} a'_0 & a'_1 & a'_2 & a'_3 \\ -a'^0 & a'^1 & a'^2 & a'^3 \end{pmatrix} = \begin{pmatrix} a_0 & a_1 & a_2 & a_3 \\ -a^0 & a^1 & a^2 & a^3 \end{pmatrix} \begin{pmatrix} \gamma & 0 & 0 & +\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ +\beta\gamma & 0 & 0 & \gamma \end{pmatrix}$$

Stopped here

Proof of the Lorentz invariance of the scalar product:

$$\begin{aligned} a' b' &= a'_\mu b'^\mu = \underbrace{\Lambda(-\vec{v})^\nu_{\ \mu}}_{\delta^\nu_\mu} a_\nu \underbrace{\Lambda(\vec{v})^\mu_{\ \eta}}_{\delta^\mu_\eta} b^\eta \\ &= \delta^\nu_\eta a_\nu b^\eta = a_\eta b^\eta = a b \\ &= a_\nu b^\nu \end{aligned}$$

The metric tensors  $g^{\mu\nu}$  and  $g_{\mu\nu}$  allow one to switch between contravariant and covariant 4-vectors forms.

$$a^\mu = g^{\mu\nu} a_\nu \quad \text{and} \quad b_\mu = g_{\mu\nu} b^\nu$$

For special relativity:  $g^{00} = -1$ ,  $g^{ii} = 1$   $i=1,2,3$   
 $g^{0i} = 0$   
 $g^{ij} = 0$   $i \neq j$

also  $g^{\mu\nu} = g^{\nu\mu}$

$$g^{\mu\nu} g_{\nu\eta} = g^\mu_\eta = \delta^\mu_\eta$$

$$\left. \begin{array}{l} g^{\mu\nu} \\ g_{\mu\nu} \end{array} \right| = \begin{pmatrix} -1 & & & 0 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$