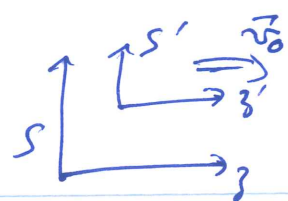


Tuesday, December 5, 2017

#1



Q: How do Contravariant 4-vectors transform?

A: $a^{\mu'} = \Lambda^{\mu}_{\nu}(\vec{v}) a^{\nu}$

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$$= \begin{pmatrix} \gamma & 0 & 0 & -\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\beta\gamma & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} a^0 \\ a^1 \\ a^2 \\ a^3 \end{pmatrix} = \begin{pmatrix} a^{0'} \\ a^{1'} \\ a^{2'} \\ a^{3'} \end{pmatrix}$$

$\Lambda(\vec{v} = v_0 \hat{z})$

Q: How do Covariant 4-vectors transform?

A: $a_{\mu'} = \Lambda_{\mu}^{\nu}(-\vec{v}_0) a_{\nu} = (a_0, a_1, a_2, a_3) \begin{pmatrix} \gamma & 0 & 0 & +\beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ +\beta\gamma & 0 & 0 & \gamma \end{pmatrix}$

\swarrow line
 \nwarrow column

(a_0', a_1', a_2', a_3')
 $= (-a^{0'}, a^{1'}, a^{2'}, a^{3'})$

$(-a^0, a^1, a^2, a^3)$

Proof of the Lorentz invariance of the scalar product:

$$a' \cdot b' = a_{\mu'} b^{\mu'} = \Lambda_{\mu}^{\nu}(-\vec{v}_0) a_{\nu} \Lambda^{\mu}(\vec{v}_0) b^{\mu} = \delta_{\nu}^{\mu} a_{\nu} b^{\mu} = a_{\nu} b^{\nu} = a \cdot b$$

Metric tensor

The metric tensors $g^{\mu\nu}$ and $g_{\mu\nu}$ allow one to switch between contravariant and covariant 4-vector forms.

~~a^{μ}~~ $a^{\mu} = g^{\mu\nu} a_{\nu}$ and $b_{\mu} = g_{\mu\nu} b^{\nu}$

for special relativity: $[g^{\mu\nu}] = [g_{\mu\nu}] = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$

also $g^{\mu\nu} = g^{\nu\mu}$

$g^{\mu\nu} g_{\nu\eta} = g^{\mu}{}_{\eta} = \delta^{\mu}_{\eta}$

"Easiest constant metric"

Examples of 4-vectors

4-position vector : $x^\mu = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} ct \\ \vec{r} \end{pmatrix}$

4-velocity : $v^\mu = \gamma \frac{d x^\mu}{dt} = \begin{pmatrix} \gamma c \\ \gamma v_x \\ \gamma v_y \\ \gamma v_z \end{pmatrix} = \begin{pmatrix} \gamma c \\ \gamma \vec{v} \end{pmatrix}$
 (object with velocity \vec{v} in S)

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

Δ ($\vec{v}_0 = v_0 \hat{j}$)
with $\vec{v}_0 \neq \vec{v}$

$$= \frac{d x^\mu}{dt} \quad \text{where } \tau = \sqrt{1 - \frac{v^2}{c^2}} \quad t = \frac{\tau}{\gamma}$$

= proper time

note:

$$v_\mu v^\mu = -c^2$$

4-acceleration : $\Gamma^\mu = \frac{d v^\mu}{d\tau} = \begin{pmatrix} \gamma \dot{\gamma} c \\ \gamma \dot{\gamma} \vec{v} + \gamma^2 \vec{a} \end{pmatrix}$

$$\frac{d v_\mu v^\mu}{d\tau} = 0$$

$\Rightarrow 2 v_\mu \frac{d v^\mu}{d\tau} = 0$

note: $\Gamma^\mu v_\mu = 0$

4-momentum : $p^\mu = m_0 v^\mu = \begin{pmatrix} m_0 \gamma c \\ m_0 \gamma \vec{v} \end{pmatrix}$

$m_{\text{relativity}} = \gamma m_0$

$$= \begin{pmatrix} E/c \\ \gamma \vec{p} \end{pmatrix}$$

relativistic kinetic energy + rest energy

rest mass

3-velocity

3-momentum

$$P_{\mu} P^{\mu} = -\frac{E_{\text{rel}}^2}{c^2} + \gamma^2 \vec{p}^2$$

$$\begin{aligned} \vec{p}_{\text{rel}} &= \gamma \vec{p} \\ &= m_0 \gamma \vec{v} \\ &= m_{\text{rel}} \vec{v} \end{aligned}$$

$$= -\frac{E_{\text{rel}}^2}{c^2} + \vec{p}_{\text{rel}}^2$$

$$= -m_0^2 \gamma^2 c^2 + m_0^2 \gamma^2 v^2$$

$$= -m_0^2 \gamma^2 c^2 \left(1 - \frac{v^2}{c^2}\right)$$

$$\Rightarrow \boxed{P_{\mu} P^{\mu} = -m_0 c^2}$$

$$\text{thus } -\frac{E_{\text{rel}}^2}{c^2} + \vec{p}_{\text{rel}}^2 = -m_0 c^2$$

$$\Leftrightarrow \boxed{E_{\text{rel}}^2 - \vec{p}_{\text{rel}}^2 c^2 = m_0^2 c^4}$$

$$\Rightarrow \boxed{E_{\text{rest}} = m_0 c^2}$$

if $\vec{p}_{\text{rel}} = 0$ (no motion at rest)

for photon: $m_0 = 0$

$$E_{\text{rel}}^2 = \vec{p}_{\text{rel}}^2 c^2$$

$$\Rightarrow \boxed{E_{\text{rel}} = |\vec{p}_{\text{rel}}| c}$$

see 09/28/2017 lecture

4-divergence:

$$\vec{\nabla} = (\partial_x, \partial_y, \partial_z) \rightarrow \frac{\partial}{\partial x^{\mu}} = \partial_{\mu} = \left(\frac{\partial}{c \partial t}, \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

(covariant)

note: missing "-" sign

Equivalent "Laplacian", i.e. D'Alembertian: $\square^2 = \frac{\partial}{\partial x^{\mu}} \frac{\partial}{\partial x^{\mu}} = \partial^{\mu} \partial_{\mu}$

$$= -\frac{1}{c^2} \frac{\partial^2}{\partial t^2} + \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$P_\mu P^\mu = -\frac{E_{rel}^2}{c^2} + \gamma^2 \vec{p}^2$$

$$\begin{aligned} \vec{p}_{rel} &= \gamma \vec{p} \\ &= m_0 \gamma \vec{v} \\ &= m_{rel} \vec{v} \end{aligned}$$

$$= -\frac{E_{rel}^2}{c^2} + \vec{p}_{rel}^2$$

$$= -m_0^2 \gamma^2 c^2 + m_0^2 \gamma^2 v^2$$

$$= -m_0^2 \gamma^2 c^2 \left(1 - \frac{v^2}{c^2}\right)$$

$$\Rightarrow \boxed{P_\mu P^\mu = -m_0 c^2}$$

thus $-\frac{E_{rel}^2}{c^2} + \vec{p}_{rel}^2 = -m_0 c^2$

$$\Leftrightarrow \boxed{E_{rel}^2 - \vec{p}_{rel}^2 c^2 = m_0^2 c^4}$$

$$\Rightarrow \boxed{E_{rest} = m_0 c^2}$$

E_0

if $\vec{p}_{rel} = 0$ (no motion at rest)

for photon: $m_0 = 0$

$$E_{rel}^2 = \vec{p}_{rel}^2 c^2$$

$$\Rightarrow \boxed{E_{rel} = |\vec{p}_{rel}| c}$$

see 09/28/2017 lecture

4-divergence:

$$\vec{\nabla} = (\partial_x, \partial_y, \partial_z) \rightarrow \frac{\partial}{\partial x^\mu} =$$

(covariant)

Why the counter-intuitive assignment?

$$\frac{\partial \phi}{\partial x^{\mu'}} = \frac{\partial \phi}{\partial x^\nu} \frac{\partial x^\nu}{\partial x^{\mu'}} = \Delta(-\vec{r}_0)_\mu^\nu$$

Equivalent "Laplacian", i.e. D'Alembertian

since $x^{\mu'} = \Delta(\vec{r}_0)_\nu^{\mu'} x^\nu$
 $\hookrightarrow x^\nu = \Delta(-\vec{r}_0)_\mu^\nu x^{\mu'}$

4-gradient: $\partial_\mu \phi = \left(\frac{1}{c} \frac{\partial \phi}{\partial t}, \vec{\nabla} \phi \right)$

4-current density:

in 3D: $\vec{J} = \rho \vec{v} \rightarrow J^\mu = ? \rho v^\mu$

↓
yes, but only if we use the rest charge density (often called the "proper charge density").

$$J^\mu = \rho_0 v^\mu \quad \text{with} \quad \rho_0 = \frac{Q}{V_0}, \quad \rho = \frac{Q}{V}$$

with $V = \frac{V_0}{\gamma}$ (length contraction)

$$\hookrightarrow \rho = \gamma \rho_0$$

Thus $J^\mu = \rho_0 v^\mu = \begin{pmatrix} \gamma \rho_0 c \\ \gamma \rho_0 \vec{v} \end{pmatrix} = \begin{pmatrix} \rho c \\ \vec{J} \end{pmatrix}$



Very important: Q is the same in all reference frames.
charge is a Lorentz invariant and is always conserved.

Relativistic Continuity Equation:

in 3D: $\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J} = 0 \Leftrightarrow \frac{\partial \rho c}{\partial ct} + \frac{\partial J_x}{\partial x} + \frac{\partial J_y}{\partial y} + \frac{\partial J_z}{\partial z} = 0$

$$\Rightarrow \boxed{\partial_\mu J^\mu = 0}$$

Lorentz Invariant Formulation of Electrodynamics

4-vector Potential (or 4-potential)

Recall that in the Lorentz gauge, Maxwell's equations take the form:

$$\begin{cases} \square^2 V = -\rho/\epsilon_0 \\ \square^2 \vec{A} = -\mu_0 \vec{J} \end{cases} \Leftrightarrow \begin{cases} \square^2 \frac{V}{c} = -\frac{\rho}{\epsilon_0 c} = -\frac{\mu_0}{\epsilon_0} \rho = -\mu_0 c \rho \\ \square^2 \vec{A} = -\mu_0 \vec{J} \end{cases} \quad J^\mu$$

This suggests that the 4-potential is $A^\mu = \begin{pmatrix} V/c \\ \vec{A} \end{pmatrix} = \begin{pmatrix} V/c \\ A_x \\ A_y \\ A_z \end{pmatrix}$

Thus we have

$$\square^2 A^\mu = -\mu_0 J^\mu \Leftrightarrow \partial_\nu \partial^\mu A^\nu = -\mu_0 J^\mu$$

Q: Can we construct 4-vectors for $\vec{E} \& \vec{B}$?

A: No! since \vec{E} -field in one frame (static charge) will acquire a \vec{B} -field in a moving frame \rightarrow 4-vector does not have enough components.
 \Rightarrow We need a mathematical object that contains both $\vec{E} \& \vec{B}$.

Electromagnetic Field Tensor $F^{\mu\nu}$

(generally referred to as "F-mu-nu")

Minkowski's space

The EM field is described in ~~4~~ 4-space with an anti-symmetric 4-tensor:

$$F^{\mu\nu} = \begin{pmatrix} 0 & E_x/c & E_y/c & E_z/c \\ -E_x/c & 0 & B_z & -B_y \\ -E_y/c & -B_z & 0 & B_x \\ -E_z/c & B_y & -B_x & 0 \end{pmatrix}$$

line \nearrow column \uparrow

note: $F^{\mu\nu} = -F^{\nu\mu}$

right hand rule mnemonic

Stopped here

How does $F^{\mu\nu}$ transform?

$$F^{\mu\nu'} = \Lambda^{\mu}_{\alpha}(\vec{v}_0) \Lambda^{\nu}_{\beta}(\vec{v}_0) F^{\alpha\beta}$$

also $F_{\mu\nu} = \begin{pmatrix} 0 & -E_x/c & -E_y/c & -E_z/c \\ E_x/c & 0 & B_z & -B_y \\ E_y/c & -B_z & 0 & B_x \\ E_z/c & B_y & -B_x & 0 \end{pmatrix}$

Note: $F^{\mu\nu} F_{\mu\nu} = 2 \left(\vec{B}^2 - \frac{\vec{E}^2}{c^2} \right)$ [true in all reference frames]

Also, it turns out that

$$F^{\mu\nu} = \frac{\partial A^\nu}{\partial x_\mu} - \frac{\partial A^\mu}{\partial x_\nu} = \partial^\mu A^\nu - \partial^\nu A^\mu$$

equivalent to $\begin{cases} \vec{E} = -\vec{\nabla}V - \frac{\partial \vec{A}}{\partial t} \\ \vec{B} = \vec{\nabla} \times \vec{A} \end{cases}$