

last time we showed
local conservation of
EM + Mechanical Energy

#1

Thursday, September 21, 2017

$$\frac{\partial}{\partial t} (\mathcal{E}_{\text{mech}} + \mathcal{E}_{\text{EM}}) = -\vec{\nabla} \cdot \vec{S}$$

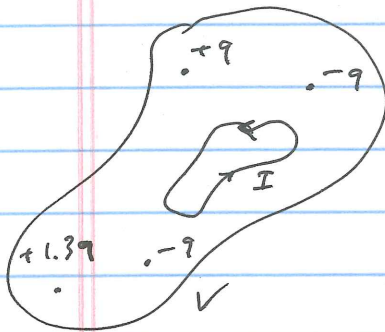
Conservation of Momentum

Just as an EM field has energy, it also carries momentum.

↳ not surprising since photons (QM) carry momentum, but this originally a classical concept.

Maxwell Stress Tensor

consider a collection of charges & currents in a volume V .



Q: what's the total EM force on all the charges in V ?

$$\begin{aligned} \underline{A:} \quad \vec{F}_{\text{total}} &= \int_V \rho(\vec{E} + \vec{v} \times \vec{B}) d^3r = \frac{d\vec{P}}{dt} \leftarrow \text{momentum} \\ &= \int_V (\rho \vec{E} + \vec{J} \times \vec{B}) d^3r \end{aligned}$$

We define the force density or force per unit volume as

$$\vec{f} = \rho \vec{E} + \vec{J} \times \vec{B}$$

$$\epsilon_0 \vec{\nabla} \cdot \vec{E} \text{ (Gauss)}$$

$$\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \text{ (Ampère's improved law)}$$

$$\Rightarrow \vec{f} = \epsilon_0 (\vec{\nabla} \cdot \vec{E}) \vec{E} + \left[\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right] \times \vec{B}$$

target this term

We note: $\frac{\partial}{\partial t}(\vec{E} \times \vec{B}) = \left(\frac{\partial \vec{E}}{\partial t}\right) \times \vec{B} + \vec{E} \times \left(\frac{\partial \vec{B}}{\partial t}\right)$

$-\nabla \times \vec{E}$ (Faraday)

$$\Rightarrow \left(\frac{\partial \vec{E}}{\partial t}\right) \times \vec{B} = \frac{\partial}{\partial t}(\vec{E} \times \vec{B}) + \vec{E} \times (\nabla \times \vec{E})$$

Thus $\vec{F} = \epsilon_0 (\nabla \cdot \vec{E}) \vec{E} + \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} - \epsilon_0 \frac{\partial}{\partial t}(\vec{E} \times \vec{B}) - \epsilon_0 \vec{E} \times (\nabla \times \vec{E})$

$$\vec{F} = -\epsilon_0 \frac{\partial}{\partial t}(\vec{E} \times \vec{B}) - \epsilon_0 \vec{E} \times (\nabla \times \vec{E}) + \epsilon_0 (\nabla \cdot \vec{E}) \vec{E} - \frac{1}{\mu_0} \vec{B} \times (\nabla \times \vec{B}) + \frac{1}{\mu_0} (\nabla \cdot \vec{B}) \vec{B}$$

$\underbrace{\frac{1}{\mu_0} (\nabla \cdot \vec{B}) \vec{B}}_{=0}$
this term makes equation more symmetric

$$= -\epsilon_0 \mu_0 \frac{\partial}{\partial t} \vec{S} + \frac{1}{2} \nabla (\vec{E}^2) - (\vec{E} \cdot \nabla) \vec{E} + \frac{1}{2} \nabla (\vec{B}^2) - (\vec{B} \cdot \nabla) \vec{B}$$

$$\begin{aligned} & (E_x \partial_x E_x + E_y \partial_y E_x + E_z \partial_z E_x) \hat{x} \\ & + (E_x \partial_x E_y + E_y \partial_y E_y + E_z \partial_z E_y) \hat{y} \\ & + (E_x \partial_x E_z + E_y \partial_y E_z + E_z \partial_z E_z) \hat{z} \end{aligned}$$

Thus,

$$\vec{F} = -\epsilon_0 \mu_0 \frac{\partial \vec{S}}{\partial t} - \frac{1}{2} \nabla (\epsilon_0 \vec{E}^2 + \frac{1}{\mu_0} \vec{B}^2) + \epsilon_0 \left\{ (\nabla \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \nabla) \vec{E} \right\}$$

$$+ \frac{1}{\mu_0} \left\{ (\nabla \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \nabla) \vec{B} \right\}$$

$\nabla \cdot ?$

we will try to get an equation of the form

$$\frac{\partial \vec{S}}{\partial t} + \nabla \cdot ? = 0$$

i.e. a continuity-type equation

Define: Maxwell's stress Tensor

$$\overleftrightarrow{T} = T_{ij} = \epsilon_0 \left[E_i E_j - \frac{1}{2} \delta_{ij} \vec{E}^2 \right] + \frac{1}{\mu_0} \left[B_i B_j - \frac{1}{2} \vec{B}^2 \delta_{ij} \right]$$

Tensor = matrix or 2-D vector, δ_{ij} = Kronecker delta
 ... n-dimensional = $\begin{cases} 1 & \text{for } i=j \\ 0 & \text{for } i \neq j \end{cases}$

Divergence of a Tensor

regular 1D vector = $\left(\vec{\nabla} \cdot \overleftrightarrow{T} \right)_j = \sum_{i=1}^3 \frac{\partial}{\partial x_i} T_{ij} = (\partial_x, \partial_y, \partial_z) \begin{pmatrix} T_{xx} & T_{xy} & T_{xz} \\ T_{yx} & T_{yy} & T_{yz} \\ T_{zx} & T_{zy} & T_{zz} \end{pmatrix}$

$x_1 = x, x_2 = y, x_3 = z$

One can show that (i.e. multiply out all the components)

$$\vec{\nabla} \cdot \overleftrightarrow{T} = \epsilon_0 \left\{ (\vec{\nabla} \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \vec{\nabla}) \vec{E} \right\} + \frac{1}{\mu_0} \left\{ (\vec{\nabla} \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \vec{\nabla}) \vec{B} \right\} - \frac{1}{2} \vec{\nabla} \left\{ \epsilon_0 \vec{E}^2 + \frac{1}{\mu_0} \vec{B}^2 \right\}$$

thus $\vec{f} = -\epsilon_0 \mu_0 \frac{\partial \vec{S}}{\partial t} + \vec{\nabla} \cdot \overleftrightarrow{T}$

$$\Rightarrow \vec{F}_{\text{total}} \Big|_V = \int_V \vec{f} d^3r = -\epsilon_0 \mu_0 \frac{\partial}{\partial t} \int_V \vec{S} d^3r + \int_V (\vec{\nabla} \cdot \overleftrightarrow{T}) d^3r$$

"Divergence theorem for tensors"

$$\oint_{\partial(V)} \overleftrightarrow{T} \cdot d\vec{s} = \text{1D vector} = \sum_j T_{ij} ds_j$$

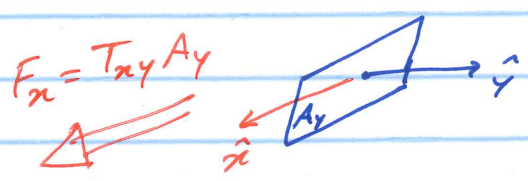
$$\Rightarrow \vec{F}_{\text{total}} \Big|_V = -\frac{d}{dt} \int_V \epsilon_0 \mu_0 \vec{S} d^3r + \oint_{\partial(V)} \overleftrightarrow{T} \cdot d\vec{s}$$

What is \vec{T} ?

\vec{T} has dimensions/units of energy density $[J/m^3]$
 or (more useful) Force per unit area $[N/m^2]$
 \rightarrow i.e. it's a "pressure".

$J = N \cdot m$

T_{xx} , T_{yy} , and T_{zz} represent pressure in the x , y , z directions, while T_{xy} is a shear (i.e. a force per unit area in the x -direction acting on a surface with direction \hat{y}).



Total force on volume V:

Newton's laws
 ! there are no known EM forces that act directly on \vec{E} & \vec{B} .

- A system of particles & fields that acts only on itself should have $\vec{F}_{total}|_V = 0$
- If there are external forces acting on V, then $\vec{F}_{total}|_V = \vec{F}_{external} = \frac{d}{dt} \vec{P}_{mech}|_V$
 when $\vec{P}_{mech}|_V$ is the mechanical momentum of the charge distribution.

Thus

$$\vec{F}_{total}|_V = \frac{d}{dt} \vec{P}_{mech}|_V = - \frac{d}{dt} \int_V \epsilon_0 \mu_0 \vec{S} d^3r + \oint_{\partial(V)} \vec{T} \cdot d\vec{s}$$

Mechanical momentum of charges / currents
"momentum"
EM forces acting on the surface of V.

This equation suggests:

(definition) $\vec{P}_{EM} = \epsilon_0 \mu_0 \int_V \vec{S} d\vec{r} = E-M \text{ momentum}$
 (momentum stored in E-M fields)

$$\vec{p}_{EM} = \frac{\epsilon_0 \mu_0 \vec{S}}{\epsilon_0 \vec{E} \times \vec{B}} = E-M \text{ momentum density}$$

↑ even static EM fields can have momentum

also, $\vec{T} =$ momentum per unit time through surface V .
 $=$ momentum flux or "current" per unit area.
 (momentum current density)

thus $\frac{d}{dt} (\underbrace{\vec{p}_{EM} + \vec{p}_{Mech}}_{\text{total momentum density}}) = \vec{\nabla} \cdot \vec{T}$ + momentum of particles entering & exiting local region

↑ note missing "-" sign → def of \vec{T}

↑ mechanical stress tensor

Total momentum (Mechanical + EM) is a locally conserved quantity

Angular Momentum

EM fields can also have angular momentum

↳ it is also conserved (but it is origin dependent)

Angular momentum density = $\vec{l}_{EM} = \vec{r} \times \vec{p}_{EM} = \epsilon_0 \vec{r} \times (\vec{E} \times \vec{B})$