

~~DC~~ DC Zeeman and DC Stark Effect

Basic Hamiltonian

Classical (non-relativistic) Hamiltonian of a charged particle (or atom) in an external field:

recall: canonical momentum: $\vec{P} \rightarrow \vec{p} - g_e \vec{q} \vec{A}$

$$(\text{i.e. } \vec{P}_{\text{canonical}} = \vec{p}_{\text{kinetic}} + g_e \vec{A})$$

$$H = \frac{1}{2m_e} (\vec{P} - g_e \vec{A})^2 + g_e V - \frac{g_e^2 q_e}{2m_e} \vec{B} \cdot \vec{s}$$

$\vec{A}(\vec{r}, t)$ $\frac{|q_e|}{4\pi\epsilon_0 r} + V_{\text{ext}}(\vec{r}, t)$

quantize
and
expand

$$H = \frac{\vec{p}^2}{2m_e} - \frac{e^2}{R} - \frac{g_e}{2m_e} (\vec{p} \cdot \vec{A} + \vec{A} \cdot \vec{p}) + \frac{g_e^2}{2m_e} \vec{A}^2 + g_e V_{\text{ext}}$$

$\vec{p} \not\parallel \vec{A}$ don't
commute

$* - \frac{g_e}{m_e} \vec{B} \cdot \vec{s}$

DC Electro-magnetic fields

DC Zeeman effect

We consider a static magnetic field (uniform)

$$\vec{B} = B_z \hat{z} = \vec{\nabla} \times \vec{A} \quad \text{with} \quad \vec{A} = \frac{1}{2} \vec{B} \times \vec{r}$$

$$= -\frac{1}{2} \left(B_z \gamma \hat{x} - B_z \gamma \hat{y} \right)$$

In magnetostatics, one operates in Coulomb gauge

$$\boxed{\vec{\nabla} \cdot \vec{A} = 0}$$

$$\text{note: } [\vec{P}, \vec{A}(\vec{R})] = -i\hbar \nabla_{\vec{R}} \vec{A}$$

$$[P_i, A_i(\vec{R})] = -i\hbar \partial_i A_i(\vec{R})$$

$$\Rightarrow \vec{P} \cdot \vec{A} - \vec{A} \cdot \vec{P} = \sum_i [P_i, A_i(\vec{R})] = -i\hbar \sum_i \partial_i A_i(\vec{R})$$

$$P_x A_x + P_y A_y + P_z A_z$$

$$= -i\hbar \underbrace{\nabla \cdot \vec{A}(\vec{R})}_{=0}$$

$$= 0$$

in magnetostatic
Coulomb gauge.

$$\text{thus } \vec{P} \cdot \vec{A} + \vec{A} \cdot \vec{P} = 2 \vec{A} \cdot \vec{P}$$

$$= 2 \left(-\frac{1}{2} (\beta_3 y \hat{i} - \beta_3 x \hat{j}) \right) \cdot (P_x \hat{i} + P_y \hat{j} + P_z \hat{k})$$

$$= -\beta_3 (y P_x - x P_y)$$

$$= \beta_3 \underbrace{(x P_y - y P_x)}_{L_3}$$

$$= \beta_3 L_3$$

$$\text{more generally } \vec{P} \cdot \vec{A} + \vec{A} \cdot \vec{P} = \vec{B} \cdot \vec{L}$$

Thus

$$H = \frac{\vec{P}^2}{2m_e} - \frac{e^2}{R} - \underbrace{\frac{q_e}{2m_e} \vec{B} \cdot \vec{L}}_{-\vec{M}_e \cdot \vec{B}} + \frac{q_e^2}{2m_e} \vec{A}^2 + q_e V_{\text{ext}} - \frac{q_e}{m_e} \vec{B} \cdot \vec{s}$$

A uniform static electric field \vec{E} can be written in potential form (Coulomb gauge)

$$V = -\vec{E} \cdot \vec{r}$$

$$\hookrightarrow V = -\vec{E} \cdot \vec{R}$$

(note: verify $\vec{E} = -\nabla V$)

thus
$$H = H_0 - \frac{q_e}{2m_e} (\vec{L} + 2\vec{s}) \cdot \vec{B} - q_e \vec{E} \cdot \vec{R} + \frac{q_e^2}{2m_e} \vec{A}^2$$

If we add in the fine structure and hyperfine structure Hamiltonian terms, then

$$H = H_0 + \underbrace{\frac{1}{2} \frac{e^2}{m_e^2 c^2} \frac{1}{R^3} \vec{L} \cdot \vec{s}}_{H_{SO} \propto \vec{L} \cdot \vec{s}} + \underbrace{\frac{A}{\hbar^2} \vec{I} \cdot \vec{s}}_{H_{HF} \propto \vec{I} \cdot \vec{s}} - \underbrace{\frac{q_e}{2m_e} (\vec{L} + 2\vec{s}) \cdot \vec{B} - q_e \vec{E} \cdot \vec{R} + \frac{q_e^2}{2m_e} \vec{A}^2}_{H_{Zeeman}}$$

H_{Stark}

$\vec{J}, \vec{S}, L^2, S^2$
are good quantum numbers

F, F_J, I^2, S^2
are good quantum numbers

$\vec{M}_I \cdot \vec{B}$
quadratic Zeeman term

I DC Zeeman Effect

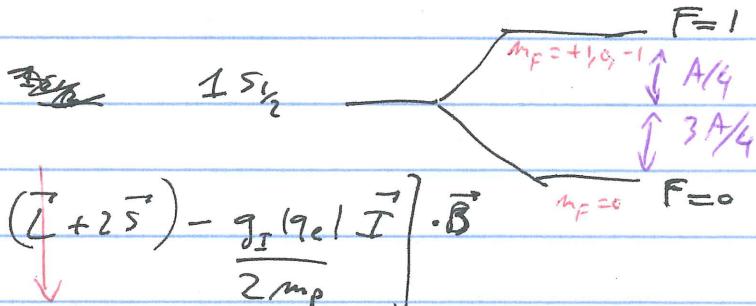
$\vec{E} = 0$, Neglect quadratic Zeeman term

Case 1: weak field limit $\mu_B B < A$

$\frac{t q_e}{2m_e}$ ↑
hyperfine A coefficient ↑

We treat ~~H_{Zeeman}~~ as a perturbation of $H_0 + H_{SO} + H_{HF}$. We work in the $\{|F, m_F\rangle\}$ basis.

example: 1s level of hydrogen



$L=0$ for s-states

Higher degenerate perturbation theory

In the ~~1s1/2~~ 1s_{1/2}, $F=1$ and 1s_{1/2}, $F=0$ manifolds, we have ~~for~~ for $\vec{B} = B_z \hat{z}$

$$\begin{aligned} [H_{\text{Zeeman}}] &= \langle F \neq 0, m_F' | H_{\text{Zeeman}} | F \neq 0, m_F \rangle \\ &= \langle F \neq 0, m_F' | \left(-\frac{g_e}{m_e} S_3 - \frac{g_I(g_e I)}{2m_p} I_3 \right) B_z | F, m_F \rangle \end{aligned}$$

we note: ($I = \frac{1}{2}$, $s = \frac{1}{2}$)

$\uparrow = +\frac{1}{2}$, $\downarrow = -\frac{1}{2}$

$$|F=1, m_F=+1\rangle = |m_I=\uparrow\rangle |m_s=\uparrow\rangle$$

$$|F=1, m_F=-1\rangle = |m_I=\downarrow\rangle |m_s=\downarrow\rangle$$

$$|F=1, m_F=0\rangle = \frac{1}{\sqrt{2}} \left[|m_I=\uparrow\rangle |m_s=\downarrow\rangle + |m_I=\downarrow\rangle |m_s=\uparrow\rangle \right]$$

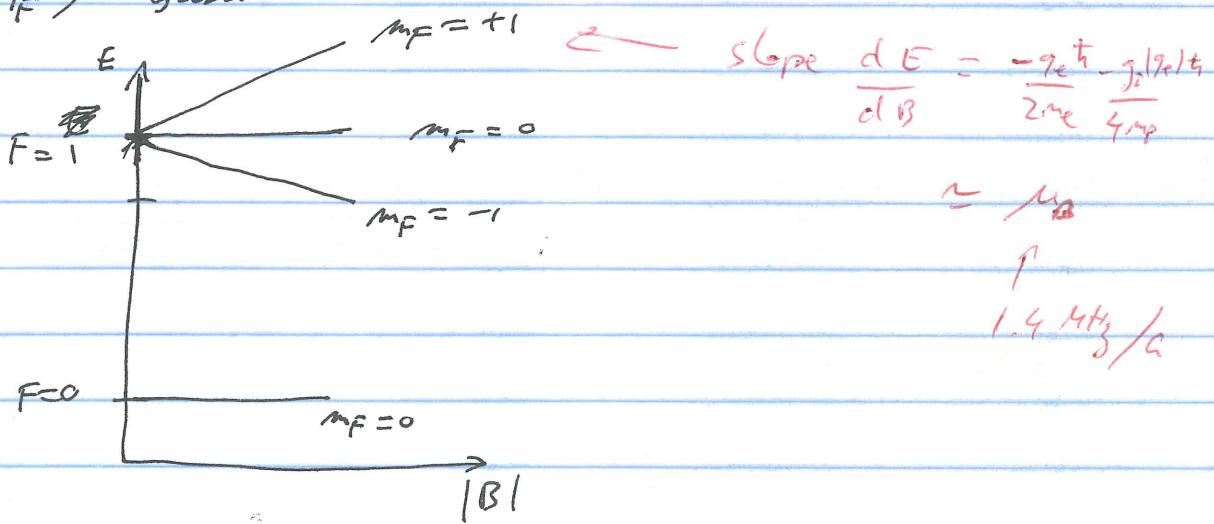
$$|F=0, m_F=0\rangle = \frac{1}{\sqrt{2}} \left[|m_I=\uparrow\rangle |m_s=\downarrow\rangle - |m_I=\downarrow\rangle |m_s=\uparrow\rangle \right]$$

$$H_{\text{Zeeman}} \Big|_{F=1} = \left(-\frac{g_e h}{2m_e} - \frac{g_I g_e h}{4m_p} \right) B_z \quad \begin{matrix} (m_F=+1) \\ \cancel{(m_F=0)} \\ (m_F=-1) \end{matrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$H_{\text{Zeeman}} \Big|_{F=0} = \cancel{(m_F=0)} [0]$$

The degeneracy is lifted and H_{Zeeman} is diagonal in the $|F, m_F\rangle$ basis



This suggests that the ~~Zeeman~~ Hamiltonian can be rewritten as

$$H_{\text{Zeeman}} = \text{cst } m_F B_z = \text{cst } \vec{F} \cdot \vec{B}$$

In fact this is an example of the Wigner-Eckart theorem

$$\vec{F} \cdot \vec{S} = (\vec{I} + \vec{s}) \cdot \vec{S} = \vec{I} \cdot \vec{S} + \vec{s}^2 = \frac{1}{2} (F^2 - S^2) + S^2 = \frac{1}{2} (F^2 + S^2 - I^2)$$

$$\vec{F} = \vec{I} + \vec{s} \quad \langle F, m_F | \vec{S} | F, m_F \rangle = \frac{\langle F, m_F | \vec{F} \cdot \vec{S} | F, m_F \rangle}{\langle F, m_F | \vec{F}^2 | F, m_F \rangle} \vec{F}$$

$$\text{similar and } \langle F, m_F | \vec{I}^* | F, m_F \rangle = \frac{\langle F, m_F | \overbrace{\vec{F} \cdot \vec{I}}^{\substack{1 \\ 2}} | F, m_F \rangle}{\langle F, m_F | \vec{F}^2 | F, m_F \rangle} \vec{F}$$

thus

$$\langle F, m_F | \vec{S} | F, m_F \rangle = \frac{F(F+1) + S(S+1) - I(I+1)}{2F(F+1)} \vec{F} \Big|_{\substack{\text{in specific} \\ F-\text{manifold} \\ \text{subspace}}}$$

$$\langle F, m_F | \vec{I} | F, m_F \rangle = \frac{F(F+1) + I(I+1) - S(S+1)}{2F(F+1)} \vec{F} \Big|_{\substack{\text{relevant} \\ F-\text{subspace}}}$$

thus

$$\left(\begin{array}{c} H_{\text{Zeeman}} \\ F-\text{subspace manifold} \end{array} \right) = \left[\frac{-g_e \hbar}{2m_e} \frac{F(F+1) + S(S+1) - I(I+1)}{F(F+1)} - \frac{g_I(g_e)}{2m_p} \frac{F(F+1) + I(I+1) - S(S+1)}{F(F+1)} \right]$$

$$x \underbrace{\vec{F} \cdot \vec{B}}_{m_p B_g}$$

note: we have effectively added $\alpha \vec{S} + \beta \vec{I}$ in an $F = \vec{I} + \vec{s}$ subspace

$$\simeq g_F \mu_B \vec{F} \cdot \vec{B}$$

$$\begin{aligned} \text{with } g_F &= \frac{F(F+1) + S(S+1) - I(I+1)}{F(F+1)} \\ &= \text{landé } g\text{-factor} \end{aligned}$$

$$\text{in our case } \begin{cases} g_F = 1 & (F=1) \\ g_F = 0 & (F=0) \end{cases}$$