

~~Thurs~~ Thursday, March 28, 2013

#1

Time Reversal Symmetry (or Reversal of motion symmetry) (continued)

definition: ~~Anti~~ Anti-linear operator

An operator A is said to be anti-linear if

$$A(c_1|\alpha\rangle + c_2|\beta\rangle) = c_1^* A|\alpha\rangle + c_2^* A|\beta\rangle$$

note: $T(c_1|\alpha\rangle + c_2|\beta\rangle) = c_1^* T|\alpha\rangle + c_2^* T|\beta\rangle$

definition: Anti-unitary operator } to be determined

An anti-linear operator A is said to be anti-linear if

$$\langle \tilde{\beta} | \tilde{\alpha} \rangle = \langle \beta | \alpha \rangle^*$$

unitary operator has

$$\langle \tilde{\beta} | \tilde{\alpha} \rangle = \langle \beta | \alpha \rangle$$

where $A|\alpha\rangle = |\tilde{\alpha}\rangle$

$$A|\beta\rangle = |\tilde{\beta}\rangle$$

note: ~~For~~ Norm and probability are still preserved

$$p = |\langle \tilde{\beta} | \tilde{\alpha} \rangle|^2 = |\langle \beta | \alpha \rangle|^2$$



$$\langle \beta | T|\alpha \rangle = \langle \beta | (T|\alpha) \rangle$$

do not try to do ~~$\langle \beta | T|\alpha \rangle$~~

Position space wave-functions

Consider the position space wave function ~~$\psi(\vec{r}, t=0) = \langle \vec{r} | \psi \rangle$~~

$$|\psi\rangle = \int d^3r \langle \vec{r} | \psi \rangle |\vec{r}\rangle$$

then $T|\psi\rangle = \int d^3r \langle \vec{r} | \psi \rangle^* \underbrace{T|\vec{r}\rangle}_{|\vec{r}\rangle}$ $T|\vec{r}\rangle = |\vec{r}\rangle$

$T =$ "reversal of motion" operator

$$\Rightarrow T|\psi\rangle = \int d^3r \langle \vec{r} | \psi \rangle^* |\vec{r}\rangle$$

\leftarrow up to some phase factor which we set to 1

thus
$$\boxed{\begin{matrix} \psi(\vec{r}) & \xrightarrow{T} & \psi^*(\vec{r}) \\ (t=0) & & (t=0) \end{matrix}}$$

Position Momentum Space wavefunctions

Note: ~~H†H~~ If $|\psi_n\rangle$ is a non-degenerate eigenstate of H ,
 then $H(T|\psi_n\rangle) = TH|\psi_n\rangle = TE_n|\psi_n\rangle = E_n(T|\psi_n\rangle)$
 $\Rightarrow T|\psi_n\rangle$ is also an eigenstate of H with eigenenergy E_n , but $\{|\psi_n\rangle, E_n\}$ is non-degenerate $\Rightarrow T|\psi_n\rangle = |\psi_n\rangle$
 $\Rightarrow \psi_n(\vec{r}) = \psi_n^*(\vec{r}) \Rightarrow \psi_n(\vec{r})$ is real
 (for spinless particles)

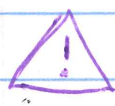
Momentum Space wavefunctions

Consider the position space wavefunction $\psi(\vec{p}, t=0) = \langle \vec{p} | \psi \rangle$
 $|\psi\rangle = \int d^3p \langle \vec{p} | \psi \rangle |\vec{p}\rangle$ "reversal of motion" operator

then $T|\psi\rangle = \int d^3p \langle \vec{p} | \psi \rangle^* \frac{T|\vec{p}\rangle}{|\vec{-p}\rangle}$ \downarrow $T|\vec{p}\rangle = |\vec{-p}\rangle$
 $= \int d^3p \langle p | \psi \rangle^* |\vec{-p}\rangle$
 $= \int d^3p \langle -p | \psi \rangle^* |\vec{p}\rangle$ substitution $k = -\vec{p}$
 $d^3k = -d^3p$

$$\Rightarrow \boxed{\psi(\vec{p}) \xrightarrow{T} \psi^*(-\vec{p})}$$

$(t=0) \qquad \qquad \qquad t=0$

 Action of T (time reversal operator) depends on basis / representation.

Angular momentum wavefunction

Case 1: ~~orbital angular momentum wavefunctions~~ orbital angular momentum wavefunctions

$$\psi(\vec{r}) = Y_l^m(\theta, \phi) \xrightarrow{T} Y_l^{m*}(\theta, \phi) = (-1)^m Y_l^{-m}(\theta, \phi)$$

real due to $(-1)^m$ factor already present in Y_l^m

thus $T |l, m\rangle = (-1)^m |l, -m\rangle$

note: $T^2 |l, m\rangle = |l, m\rangle$, also $\Psi(r) \xrightarrow{T^2} \Psi(r)$.

Spin - 1/2 wavefunctions

$T |\uparrow\rangle = ?$ or $T |\downarrow\rangle = ?$

We will admit that anti-unitary operators can be written in the form $A = UK$, where U is unitary (linear) and K perform the ~~op~~ complex conjugation operation:

$$K (c_1 |\alpha\rangle + c_2 |\beta\rangle) = c_1^* K|\alpha\rangle + c_2^* K|\beta\rangle = c_1^* |\alpha\rangle + c_2^* |\beta\rangle$$

(if $|\alpha\rangle$ and $|\beta\rangle$ are basis kets)

So $T = U_T K$

\swarrow Unitary ~~time~~ operator for time reversal (or reversal of motion)
 \nearrow complex conjugator acts to the right (on a ket)

We know $T \vec{S} T^{-1} = -\vec{S}$

$\Rightarrow T S_i T^{-1} = -S_i$

$\Rightarrow U_T K S_i (U_T K)^{-1} = -S_i$

$\Rightarrow U_T K S_i \underbrace{K^{-1} U_T^{-1}}_K = -S_i$ (clearly $K^{-1} = K$)

We note that in S_z eigenbasis we can write ~~the~~ $\{|\uparrow\rangle, |\downarrow\rangle\}$

$S_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $S_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$K S_z K = S_z K^2 = S_z$; $K S_x K = S_x K^2 = S_x$; $K S_y K = -S_y K^2 = -S_y$

$\Rightarrow T S_z T^{-1} = -S_z$

$U_T S_x U_T^{-1} = -S_x$; $U_T S_y U_T^{-1} = S_y$

$U_T K S_z K U_T^{-1} = -S_z \Rightarrow U_T S_z U_T^{-1} = -S_z$

One can show that $U_T = e^{i\phi} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ satisfies these ~~requirements~~ requirements

set $\phi=0$ \downarrow $= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ $\left| \begin{array}{l} T|\uparrow\rangle = |\downarrow\rangle \\ T|\downarrow\rangle = -|\uparrow\rangle \end{array} \right.$

If we apply T twice: $TT = T^2 = \begin{pmatrix} 0 & 1 & 0 & 1 \\ -1 & 0 & -1 & 0 \end{pmatrix}$

$$T^2 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = -\mathbb{1}$$

thus $T^2 |\uparrow\rangle = -|\uparrow\rangle$
 $T^2 |\downarrow\rangle = -|\downarrow\rangle$

If you time reverse a spin- $\frac{1}{2}$ twice, you don't get the same thing back

but $T^4 = 1$

Surprisingly? ~~sort of~~ but recall that the rotation operator is $\mathcal{D}(\theta) = \exp\left(-i \frac{\vec{J} \cdot \hat{n}}{\hbar} \theta\right)$

for $\hat{n} = \hat{z}$ in a 2-D system ("spin- $\frac{1}{2}$ ")

$$\mathcal{D}(\theta) = \exp\left(-i \frac{S_z}{\hbar} \theta\right) = \begin{matrix} |\uparrow\rangle & |\downarrow\rangle \\ \langle\uparrow| & \langle\downarrow| \end{matrix} \begin{pmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{+i\theta/2} \end{pmatrix}$$

$\mathcal{D}(\theta=2\pi) |\uparrow\rangle = -|\uparrow\rangle$

but $\mathcal{D}(\theta=4\pi) |\uparrow\rangle = +|\uparrow\rangle$

More generally, one can show that

$$T^2 |j\text{-half-integer}\rangle = - |j\text{-half-integer}\rangle$$

$$T^2 |j\text{-integer}\rangle = + |j\text{-integer}\rangle$$

If we change our phase convention to $\phi = \pi/2$

$$U_T = e^{i\pi/2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$$

then

$$T |j, m\rangle = i^{2m} |j, -m\rangle$$

$$\& \text{ (which is consistent with } T |Y_l^m\rangle = (-1)^m |Y_l^{-m}\rangle)$$



this phase convention is not consistent with the one that gives $J_{\pm} |j, m\rangle = \pm \sqrt{(j \mp m)(j \pm m + 1)} |j, m \pm 1\rangle$

T-violation

~~As~~ Generally the Hamiltonian is T-even (i.e. $THT^{-1} = H$ or $[T, H] = 0$), but the ~~standard~~ Standard Model and extensions to it (e.g. ~~supersymmetry~~ supersymmetry) predict T-odd Hamiltonian terms, including an electron dipole moment

$\vec{d}_e \propto \vec{S}$ so that

$$H_{\text{edm}} = -\vec{d}_e \cdot \vec{E} = \text{cst } \vec{S} \cdot \vec{E}$$

\vec{E}_{total}
(not $\vec{E}_{\text{external}}$)

[see Sakurai]
problem # 5.15

note: H_{edm} is also parity odd $\forall H_{\text{edm}} + H_{\text{edm}} T = 0$

method: look for an \vec{E} -dependent Zeeman shift \rightarrow so far no EDM detected